

# ARC FILTERS USING ONLY FOLLOWERS

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## Abstract

Several structures of the active RC filters using non-inverting voltage unity-gain followers and dual current positive followers are given in this paper. These structures can be suitably implemented by the positive second generation current conveyors or by the transimpedance operational amplifiers. A symbolical analysis using SNAP and a simulation by PSpice have been made to confirm the given theoretical approach.

## Keywords

analogue signal processing, active RC filters, voltage and current unity-gain followers.

## 1. Introduction

The recent progress of the current mode technology [3] has allowed the implementation of new monolithic IC active components and / or functional blocks, with higher frequency operation and wider dynamic range as compared with the classical opamps.

Such components are e.g. the second generation current conveyors (CC II) and the transimpedance operational amplifiers (TIOA) in Fig. 1.

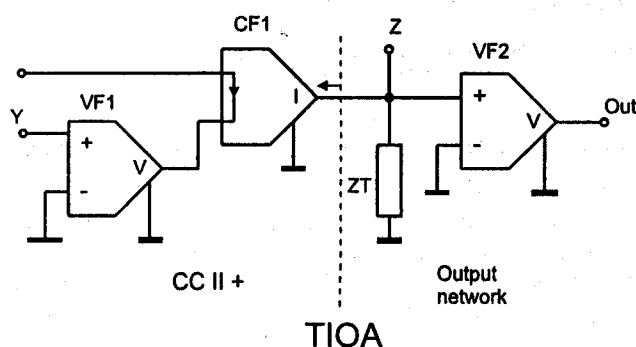


Fig. 1 Model of the basic current conveyor CC II and the transimpedance operational amplifier using voltage and current followers

The new functional block titled differential voltage current conveyor (DVCC) [4], which is a fifth-port (Fig. 2a) based on the CC II, has a model given in Fig. 2b.

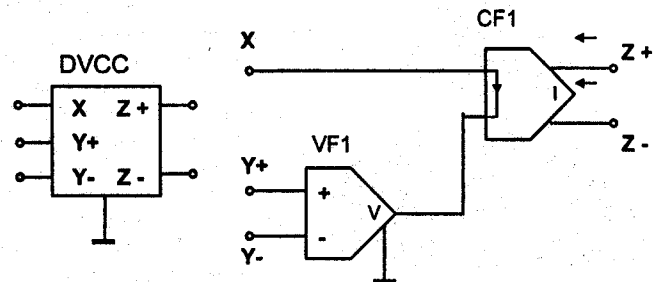


Fig. 2. Differential voltage current conveyor  
a) block symbol,  
b) suitable model

On the face of these models (Fig. 1 and Fig. 2) one can see, that the both mentioned functional blocks consist in detail of the two types of subcircuits only, namely the voltage and current followers. It is the reason that the realisation of given transfer functions using the followers has recently received considerable attention in the literature [1], [2]. The method allows an uniform approach and simple design.

## 2. Voltage and dual current followers

The unity gain cells given above (Fig. 1) are namely, voltage follower (VF) described by

$$i_x = 0, \quad v_x = (\pm) v_y, \quad (1)$$

and the dual current follower (CF) described dually

$$v_x = 0, \quad i_x = (\pm) i_y. \quad (2)$$

Note that the ports of the buffers can be connected as follows:

- single input and single output (SISO),
- differential input and single output (DISO),
- single input and differential output (SIDO),
- differential input and differential output (DIDO).

Furthermore our attention is constrained on the non-inverting or positive followers only, specially on the positive current followers (CF+), with differential input and single output (DISOCF+). The reason is, that these structures current follower can be easily implemented by the commercially available component AD 844, what is quite different to the reference [1].

These followers have become as essential elements in the analogue signal processing, namely in the voltage and in the current mode too. They have brought novel simple conception in simulation process and circuit design, which was firstly given in references [1] and [2].

### 3. Integrators using followers

For the purpose of the synthesis of n-order filters, we are taking now, 1-st order low-pass filter, as a suitable building subcircuit. The Fig. 3 shows a conventional voltage integrator using voltage and current followers, namely the VF1 and the CF1. The transfer function of this circuit has the single form

$$K = \frac{V_{out}}{V_{inp}} = \pm \frac{R_2}{R_1} \frac{1}{1 + sC_1 R_2} \quad (3)$$

If the resistor  $R_2$  is not presented in the circuit of Fig. 3 a pure integrator is obtained, when

$$K = \frac{V_{out}}{V_{inp}} = \pm \frac{1}{sC_1 R_1} \quad (4)$$

and in time domain

$$v_{out}(t) = \frac{1}{R_1 C_1} \int v_{inp}(t) dt \quad (5)$$

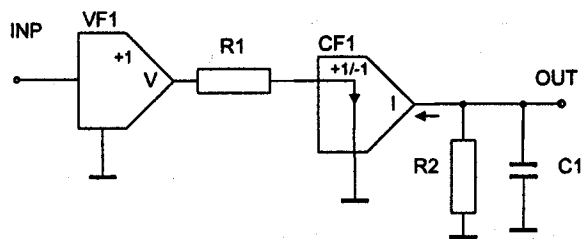


Fig. 3 Voltage integrator using followers

A modification of the above integrator for the conveyors CC II (+) is given in Fig. 4.

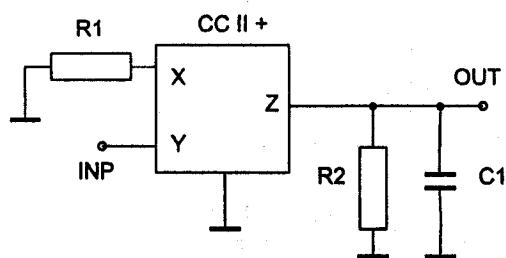


Fig. 4 Voltage integrator using current conveyors

Using the adjoint transformation from [3], the current integrator described by

$$i_{out}(t) = \frac{1}{R_1 C_1} \int i_{inp}(t) dt \quad (6)$$

is proposed as shown in Fig. 5.

### 4. Biquadratic structures with followers

Other building block is the biquad. The first proposed biquadratic structure B4F-A, using four followers, namely

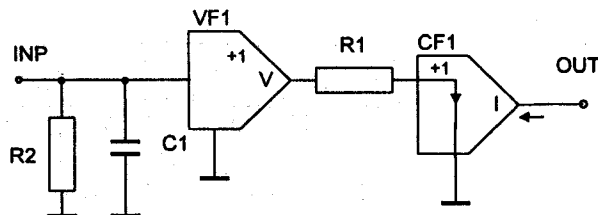


Fig. 5 Current integrator using followers

two voltage ones (VF1, VF2) and two dual positive current ones (CF1, CF2), both with differential input and single output, is shown in Fig. 6. The routine symbolical nodal analysis, aided by computer tool SNAP, results in the following transfer function for the *Out-A*

$$K_A(s) = \frac{V_{out}^{(A)}}{V_{in}} = \frac{Y_1 Y_2}{Y_1 Y_3 + Y_3 Y_5 + Y_2 Y_4} \quad (7)$$

and similarly for the *Out-B*

$$K_B(s) = \frac{V_{out}^{(B)}}{V_{in}} = \frac{-Y_1 Y_3}{Y_1 Y_3 + Y_3 Y_5 + Y_2 Y_4} \quad (8)$$

It is evident, that the coefficients of the transfer functions are given by the element values quite independently. This is the basic advantage of the structure B4F-A compared with the B4F-B, given below.

If the gains of the followers are not exactly unity, but

$$E = 1 + \delta v \quad \text{and} \quad F = 1 + \delta i, \quad (9)$$

then the transfer function (7) would be

$$K_A(s) = \frac{-E_1 E_2 F_2 Y_1 Y_2}{Y_1 Y_3 + Y_3 Y_5 + E_1 E_2 F_1 F_2 Y_2 Y_4} \quad (10)$$

what allows to evaluate the associated tracking errors and corresponding real inherent features.

The other biquadratic structure B4F-B using four followers is shown in Fig. 7. There the first current follower CF1 has non-standard connection of the output port, what brings a difficulty with practical implementation, e.g. using the TIOA. A modification of this structure has been given in [2], namely using one negative (CF1) and one positive current follower (CF2), both standard grounded.

The symbolical analysis of the circuit in Fig. 7 results in the simpler transfer function as follows

$$K_A(s) = \frac{V_{out}}{V_{in}} = -\frac{Y_1 Y_3 + Y_2 Y_6}{Y_3 Y_4 + Y_5 Y_6} \quad (11)$$

To obtain a biquadratic function from (11), some from the Y must be taken as a parallel connection of two RC elements, what is illustrated in Tab. 2.

Other structure using only three followers was presented in [1]. Similar configuration B3F is given in Fig. 8. There the analysis yields the transfer functions with similar form as the above (7), (8) for the B4F-A, namely

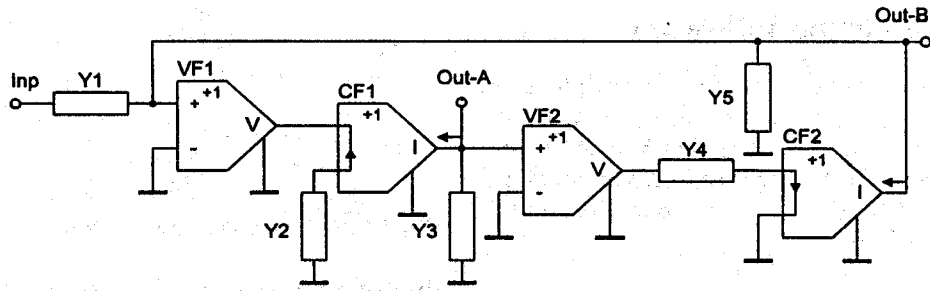


Fig. 6 Structure B4F-A of the biquad, using four followers VF and CF+.

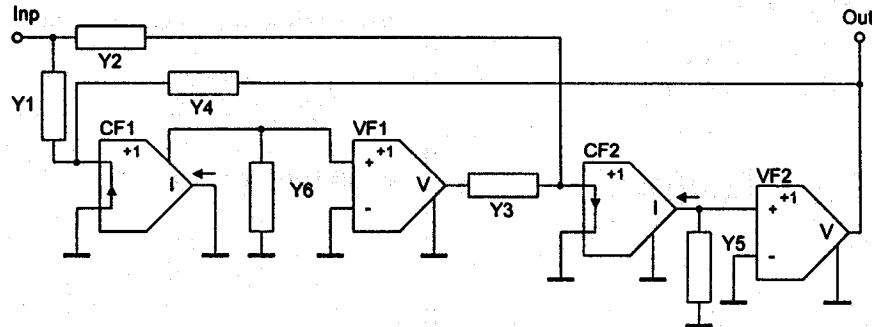


Fig. 7 Structure B4F-B of the biquad with four followers.

$$K_A(s) = \frac{V_{out}^{(A)}}{V_{in}} = \frac{-Y_1 Y_3}{Y_1 Y_2 + Y_2 Y_4 + Y_3 Y_4}, \quad (12)$$

$$K_B(s) = \frac{V_{out}^{(B)}}{V_{in}} = \frac{Y_1 Y_2}{Y_1 Y_2 + Y_2 Y_4 + Y_3 Y_4}. \quad (13)$$

Note that other lower number of the followers can not be good utilised in today practical implementations using the transimpedance amplifiers. However the both given structures B4F-B and B4F-A employ two transimpedance amplifiers only.

Tab. 1: Variants of the filter implementation using the structure B4F-A (Fig. 6)

Variant	Admittance					Output	
	$Y_1$	$Y_2$	$Y_3$	$Y_4$	$Y_5$	A	B
B4FA-1	$sC_1$	$R_2^{-1}$	$sC_3$	$R_4^{-1}$	$R_5^{-1}$	BP	HP
B4FA-2	$R_1^{-1}$	$R_2^{-1}$	$sC_3$	$R_4^{-1}$	$sC_5$	LP	BP
B4FA-3	$R_1^{-1}$	$sC_2$	$R_3^{-1}$	$sC_4$	$sC_5$	BP	LP
B4FA-4	$sC_1$	$sC_2$	$R_3^{-1}$	$sC_4$	$R_5^{-1}$	HP	BP

Tab. 2: Variants of the filter implementation using the structure B4F-B (Fig. 7).

Variant	$Y_1$	$Y_2$	$Y_3$	$Y_4$	$Y_5$	$Y_6$	Output
B4FB-1	$R_1^{-1}$	-	$sC_3$	$R_4^{-1}$	$R_5^{-1}$	$sC_6 + R_6^{-1}$	LP
B4FB-2	-	$R_2^{-1}$	$sC_3$	$R_4^{-1}$	$R_5^{-1}$	$sC_6 + R_6^{-1}$	BP
B4FB-3	-	$sC_2$	$sC_3$	$R_4^{-1}$	$R_5^{-1}$	$sC_6 + R_6^{-1}$	HP

Tab. 3: Variants of the filter implementation using the structure B3F (Fig. 8).

Variant	$Y_1$	$Y_2$	$Y_3$	$Y_4$	Out-A	Out-B
B3F-1	$sC_1$	$sC_2$	$R_3^{-1}$	$R_4^{-1}$	BP	HP
B3F-2	$R_1^{-1}$	$R_2^{-1}$	$sC_3$	$sC_4$	BP	LP

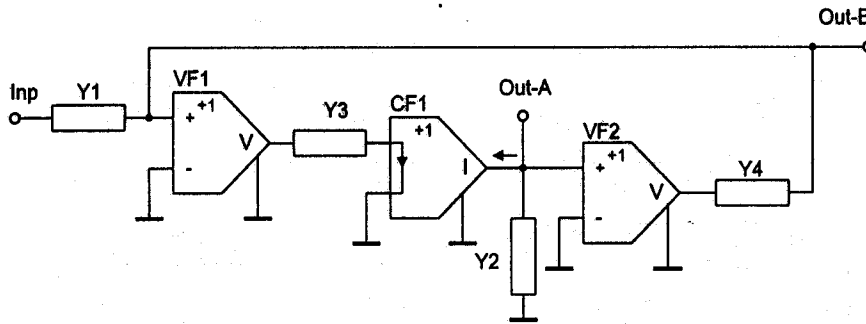


Fig. 8 Structure B3F3 of the biquad with three followers.

### 5. ARC filters using given structures

The particular choice of the admittance's  $Y$ , in the structure B4F-A (Fig. 6), can be easily determine by the denominator in the eq. (7) or (8), to give the 2<sup>nd</sup> order polynomial of the variable  $s$ . Note that, we assume for each  $Y$  the  $R$  or the  $C$ , as a single component only. All suitable combinations in four particular variants are given in the Tab. 1. Similarly for the structures B4F-B and B3F suitable variants are given in the Tab. 2 and Tab. 3.

Nevertheless we pay more our attention on the B4F-A. There the variants (Tab. 1) are not practically equivalent, due to the influence of the parasitic driving impedances of the real followers, specially the input resistance ( $R_x$ ) of the current followers ( $CF_1$  and  $CF_2$ ). Better is if the parasitic  $R_x$  interacts as simple sum with the resistors  $R_2$  and  $R_3$ , what is in the B4FA-1 and B4FA-2. In this case the basic filter parameters ( $\omega_b$ ,  $Q$ ) are charged with small errors only. In other configurations (B4FA-3 and B4FA-4) the resistances  $R_x$  interact with the capacitors  $C_2$  and  $C_3$  and these time constants influence more the filter parameters.

### 6. Modification for current conveyors

The ARC structures given above can be fairly modified for the implementation using the current conveyors CC II. An example of this modification of the structure B4F-A (Fig. 6) is obtained by changing the orientation of the input port and along with the sign of the parameter  $F = -1$  of the CF 2 (Fig. 6). Then the practicable implementation using two CC II+/- is shown in Fig. 9. The circuit was symbolical analysed by SNAP to obtain the same results (7) and (8) given above.

### 7. Simulation results

To illustrate a design of the biquad we take the variant B4FA-2 (Tab. 1). There the transfer function (8) becomes in this form

$$K_B(s) = \frac{sC_3G_1}{s^2C_5C_3 + sC_3G_1 + G_2G_4} \quad (14)$$

From the eq. (14), the natural frequency (15) and the quality factor of the poles (16) are given as follows

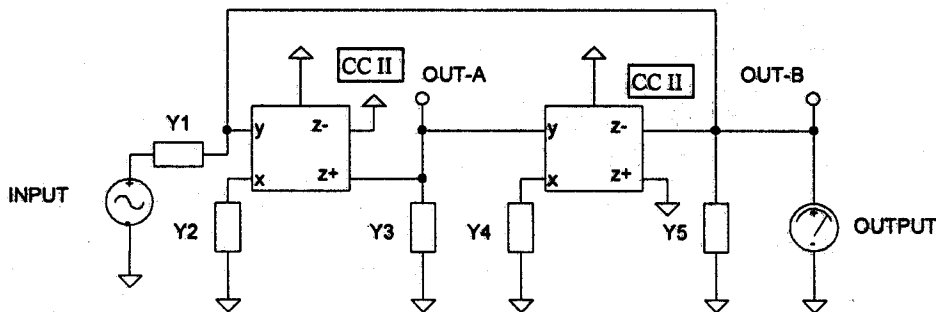


Fig. 9 Implementation of the structure B4F-A (Fig. 6) using current conveyors CC II+/- (Simulation in SNAP)

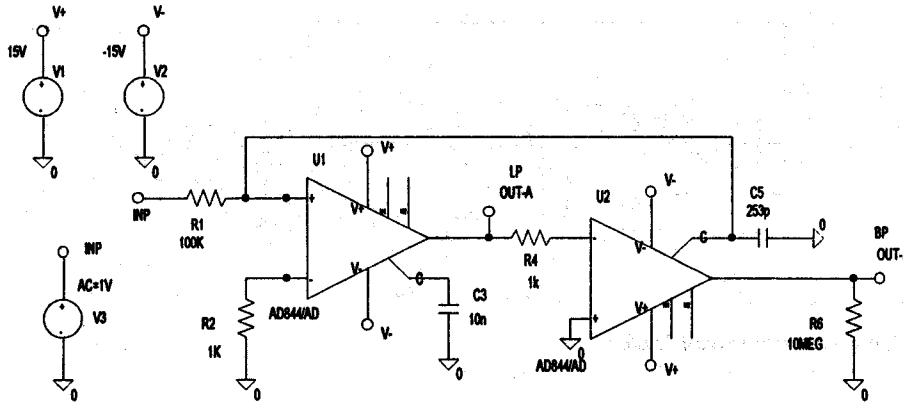


Fig. 10 Implementation of the structure B4FA (Fig. 6), the variant B4FA-2 (Tab. 1), using the TIOA (AD 844). (Simulation in PSpice)

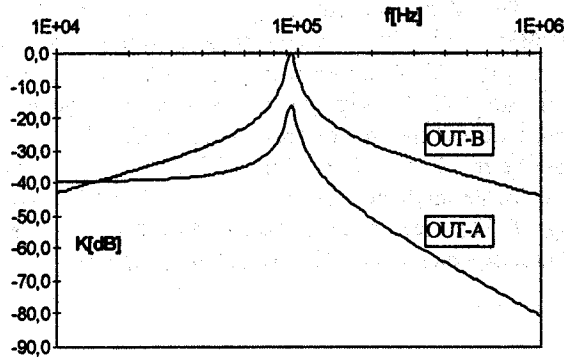


Fig. 11 Magnitude responses of the filter B4FA from Fig. 10.

$$\omega_o = \frac{1}{\sqrt{C_5 R_2 C_3 R_4}}, \quad (15)$$

$$Q = \frac{R_1}{\sqrt{R_2 R_4}} \sqrt{\frac{C_5}{C_3}}. \quad (16)$$

The given equations (15) and (16) have been used for the design of the ARC filter with this specification:  
2<sup>nd</sup> order BP,  $f_o = 100 \text{ kHz}$ ,  $Q = 16$ .

The designed circuit B4FA-2 (Fig. 6) has the following values:

$$R_1 = 100 \text{ k}\Omega, \quad R_2 = R_4 = 1 \text{ k}\Omega, \\ C_3 = 10 \text{ nF}, \quad C_5 = 253 \text{ pF}.$$

This filter was modified for the transimpedance operational amplifiers AD 844 (Fig. 10) and simulated with the PSpice, using professional macro models. The resulting magnitude responses of the both outputs (Out-A, Out-B) are in Fig. 11. One can see, that there is a wide frequency range without distortion. So the simulations are well confirming the theoretical assumptions.

Furthermore note that the all sensitivities of the given circuits are small

$$S_{\gamma^o} < 1, \quad S_{\gamma^Q} < 1. \quad (17)$$

### 8. Filters in current mode

If the signal is required as the current to be processed, then the adjoint transformation from [3] can be used, to obtain the other adjoint structures in the current mode (CM). Illustrating this method, the biquadratic structure of the B3B (Fig. 8) is taken and transformed in the adjoint circuit in the CM, as shown in Fig. 12. There the current gain has the same symbolical form as the voltage one, given above, namely (12) and (13).

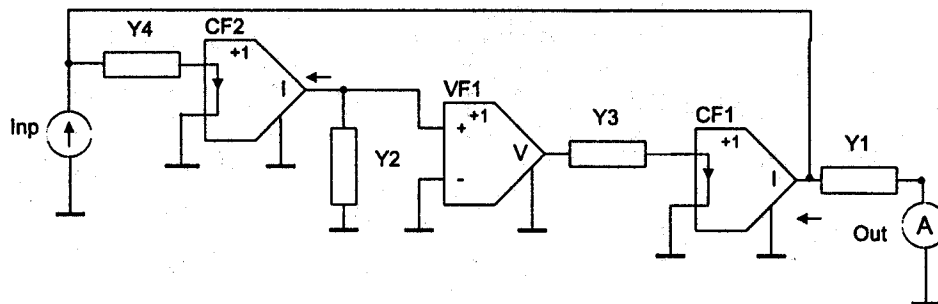


Fig. 12 The biquadratic structure B3F3 in current mode.

## 9. Conclusion

The given structures of the biquadratic ARC filter using the non-inverting voltage followers and the dual positive current followers is evidently right choice for high frequency applications. These filters can be practically implemented by the two commercially available transimpedance operational amplifiers AD 844. The simulated results have confirmed this conclusion.

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## References

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Tomáš DOSTÁL was born in Brno, in 1943. He received the CSc. (Ph.D) and DrSc. degree in electrical engineering from the Technical University Brno in 1976 and 1989 respectively. From 1973 to 1978, and from 1980 to 1984, was with Military Academy Brno, from 1978 to 1980 with Military Technical College Baghdad. Since 1984 he has been with the Technical University Brno, where he is now Professor of Radioelectronics. His present interests are in the circuit theory, filters, switched capacitor networks and circuits in current mode.

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