

Broadband SHF Direction-Finder

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Abstract. The original design of the compact broadband direction-finder is presented in this paper. The cylindrical monopole antenna serves as a primary source of the reflector-type antenna. “Zero-amplitude” technique is used for bearing the SHF sources. The model experiments with the proposed direction-finder prototype in the frequency band 6 GHz – 11 GHz have been carried out.

Keywords

Mobile communication, direction-finder, antenna measurement, antenna radiation pattern, “zero-amplitude” technique.

1. Introduction

Nowadays the radio systems operating at frequencies higher than 1GHz are widely used. The advancement to the state-of-the-art backbone links such as WiMAX standards-based technology compels moving to the higher frequencies up to 66 GHz that will allow one to deliver capacity of up to 40 Mbps per channel, for fixed and portable access applications. With these remarks in mind, the source location problem should be overcome. The numerous approaches and techniques are known for detecting, identifying and classifying various types of disturbance sources [1]-[6]. Nevertheless, the compact broadband mobile direction-finders with high-rapid rates are required.

In this paper we present the reflector antenna for the compact X-band direction-finder and the results of model experiments.

2. Design and Optimization of the Reflector Antenna

Schematic view of the novel reflector antenna as the element of the direction-finder system is shown in Fig.1. This antenna consists of the main reflector and the primary source as the cylindrical monopole antenna located in the main reflector focus.

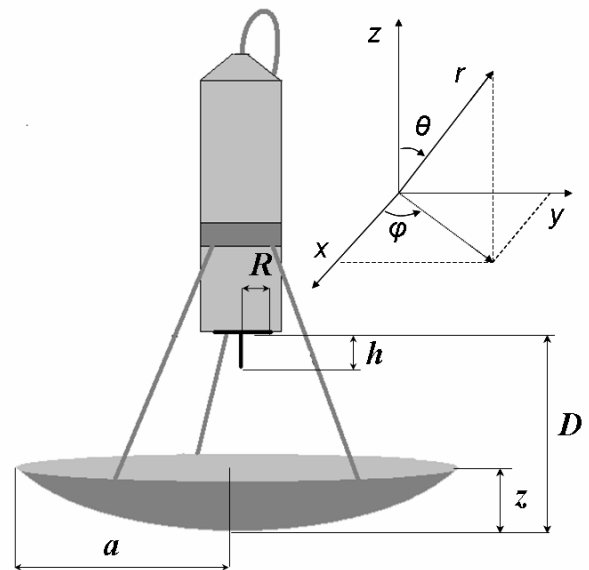


Fig. 1. Antenna design.

The monopole antenna is chosen from the following requirements, namely:

- the ground plane should have a minimal size to diminish the blockage effect;
- the EM field distribution on the reflector aperture should provide the maximal utilization factor of the reflector surface;
- the radiation pattern shape should remain virtually the same in the limits of the antenna bandwidth.

The investigations carried out by us earlier [7] have shown a possibility to control effectively the radiation characteristics of the cylindrical monopole antenna (Fig.2.) by changing the monopole height and the ground plane size. We have carried out the measurements of the monopole antenna characteristics when the geometrical parameters of antenna differed within the following limits: the monopole height $7.5\text{mm} < h < 22.5\text{mm}$, and the ground plane radius $7.5\text{mm} < R < 22.5\text{mm}$ with the step 7.5mm.

Since the primary source is located in the near-field of the main reflector, we focused on the investigations of near-field distributions in the radiating region of the mono

pole antenna. The measurements were performed by means of the methods, facilities and special probe described in [8].

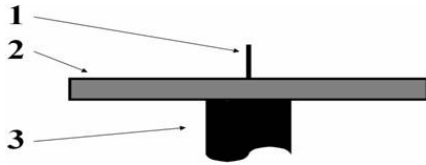


Fig. 2. Cylindrical monopole antenna: 1- monopole; 2- ground plane; 3- coaxial.

In the framework of these investigations some regularity in the near-field distributions have been determined for the fixed monopole height, namely: (i) the ground plane reduction results in the wave-beam narrowing and EM field power increasing outside the ground plane; (ii) the distance between the amplitude maxima in the near-field distribu-

tions increases with the ground plane radius increase. Such behavior of the EM field in the “radiating” region leads to the changes in the radiation patterns. For example, the near-field distributions and the radiation patterns of antenna with the monopole height $h=7.5\text{mm}$ are shown in Figs. 3 and 4. Thick solid lines at the bottom of pictures in Fig. 3 show the ground plane size of the monopole antenna. As one sees from Fig. 4, there are different shapes of radiation patterns depending on the ground plane size. At that, with the ground plane radius increase the beamwidth increases, too. From the measurements of near-fields and radiation patterns we may conclude that the EM field distributions of the monopole antenna with parameters $h=7.5\text{mm}$, $R=15\text{mm}$ (Fig. 3b and 4b) is the most acceptable one since, on one hand, the wave beam is wide enough for the effective illumination of the main reflector. On the other hand, the ground plane size is small from the feed blockage of the main reflector point of view.

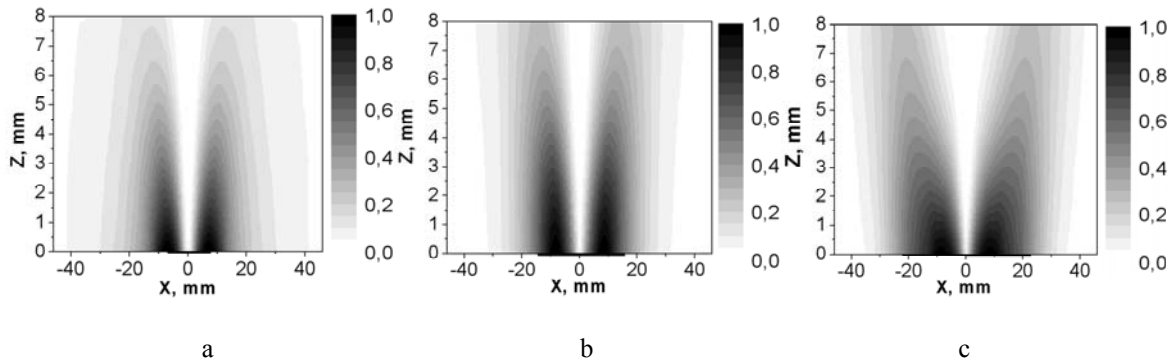


Fig. 3. Measured near-field distributions of the monopole antenna at the frequency $f=9.89$ GHz with different ground plane radii: $R=7.5$ mm (a); $R=15$ mm (b); $R=22.5$ mm (c)

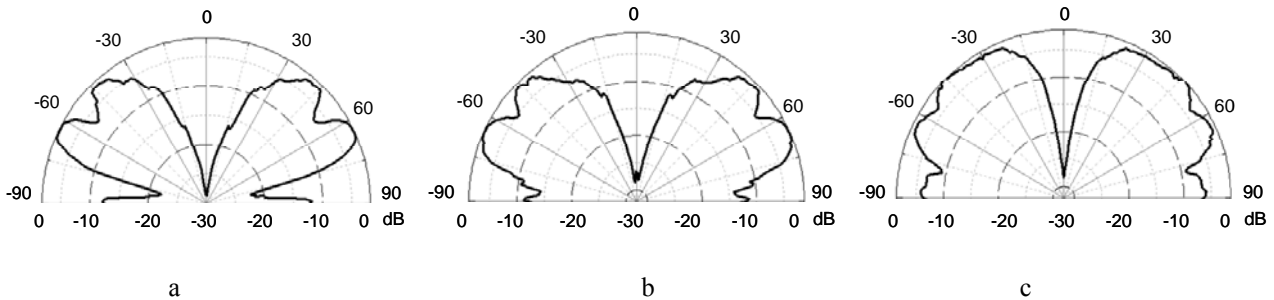


Fig. 4. Measured radiation patterns of the monopole antenna at the frequency $f=9.89$ GHz with different ground plane radii: $R=7.5$ mm (a); $R=15$ mm (b); $R=22.5$ mm (c)

Based on the experimental results noted above we have carried out the simulations of radiation patterns of the reflector antenna with a primary source as the monopole antenna with monopole height $h=7.5$ mm, $R=15$ mm, the focal length of the parabolic main reflector $D=55$ mm and the aperture radius of the main reflector $a=80$ mm. The calculated radiation pattern of reflector antenna shows a high level of the side lobes (Tab. 1, Fig. 5a).

Therefore the computational modeling of the reflector antenna with parameters changed in the limits: $7.5 \text{ mm} < h$

$< 22.5 \text{ mm}$, $7.5 \text{ mm} < R < 22.5 \text{ mm}$, $50 \text{ mm} < a < 100 \text{ mm}$, and $40 \text{ mm} < D < 60 \text{ mm}$ was carried out. As a result of investigations noted above, the following optimal parameters of the reflector antenna were chosen, namely: the aperture radius of the main reflector is $a=80$ mm, the monopole height $h=22.5$ mm, the ground plane radius $R=22.5$ mm, the focal length of the parabolic main reflector $D=55$ mm. As can be seen from Fig. 5b and Tab. 1, the calculated radiation pattern of the reflector antenna with optimal geometric parameters produces the radiation pattern with the low level of the first side lobe.

h, R, (mm)	$\Delta\theta$ (degree)	$\Delta\theta'$ (degree)	Side lobe level (dB)	Gain (dB)
Theory				
7.5, 15	9	1.5	-15	16
22.5, 22.5	10	1.5	-21	18
Experiment				
22.5, 22.5	7	1.5	-19	17

Tab. 1. The characteristics of reflector antennas with different parameters.

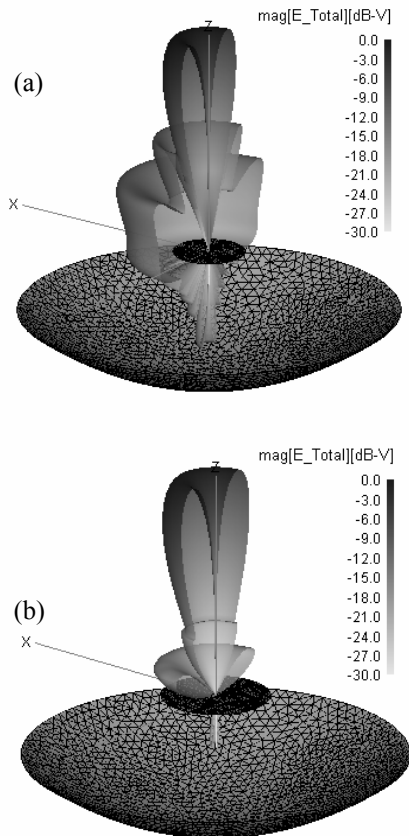


Fig. 5. Calculated radiation patterns of the reflector antennas with non optimal (a) and optimal (b) parameters.

The reflector antenna prototype with optimal geometrical parameters has been manufactured. The radiation patterns of reflector antenna prototype were measured in the sweep mode of the SHF oscillator [9] that allows one to analyze quickly the radiation pattern behavior in the limits of antenna bandwidth.

The measurements carried out in the far-field region have shown that the given reflector antenna produces the mono-beam conic radiation pattern (Fig. 6a) in the frequency band 6 GHz – 11 GHz (Fig. 6b) with the elevation angle of peak directivity $\theta=10^{\circ}$. The experimental radiation pattern is narrower than the calculated one but the first side lobe level is higher (Tab. 1). It is worth noting that the power signal ratio in the antenna axis and in the main lobe

maximum is less than -20 dB. At that the important characteristic of antenna from the point of view of its applying as a direction-finder antenna is the angle $\Delta\theta'$. This angle determines the antenna position in which the signal increases on 3 dB in comparison with the minimal one. For the antenna prototype this angle is small that allows us to expect high space resolution of the proposed direction-finder.

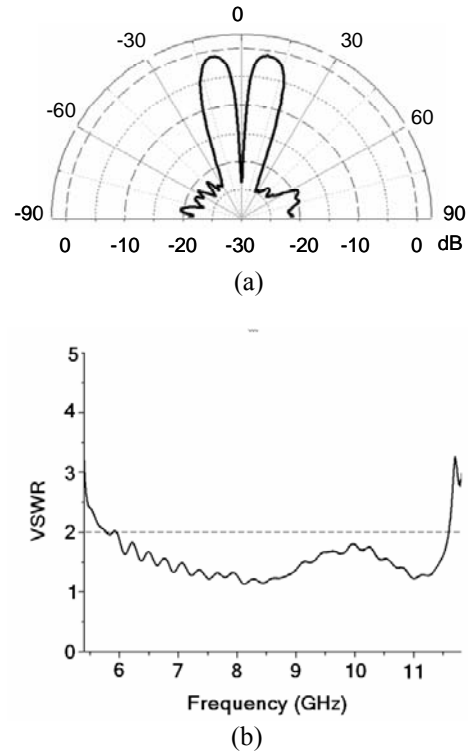


Fig. 6. Measured radiation pattern at $f=10$ GHz (a) and VSWR (b) of the direction-finder antenna prototype: $h=22.5$ mm, $R=22.5$ mm, $D=55$ mm, $a=80$ mm.

With the aim to study the process of radiation shaping of the reflector antenna and to choose the optimal dimensions of the supporting antenna elements, as well as their mutual arrangement, we have carried out the simulations and measurements of EM field distributions in the radiating region of the reflector antenna prototype. The near-field distributions measured at the frequency $f=10$ GHz are shown in Fig.7a for the optimized direction-finder antenna prototype. As one sees from this picture one has the main lobe and the weak side lobe with a power level around -15dB.

Computational modeling of the near-field distribution at the same frequency $f=10$ GHz (Fig. 7b) points out a qualitative agreement with the experiment. However, the calculated side lobe level is a little lower (around -20dB). Notice, that the power signal ratio in the antenna axis and in the main lobe maximum is higher than -30 dB. Thus, we can pronounce that the supporting elements do not disturb the EM field distribution in the radiating region of antenna prototype.

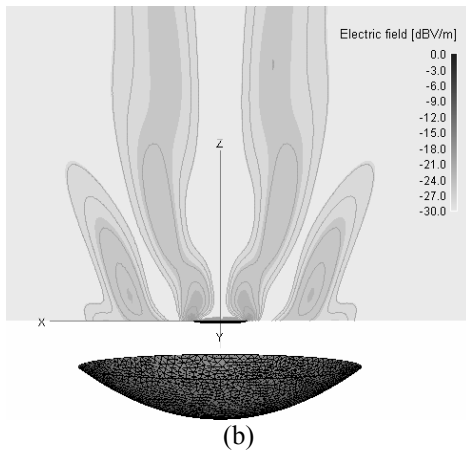
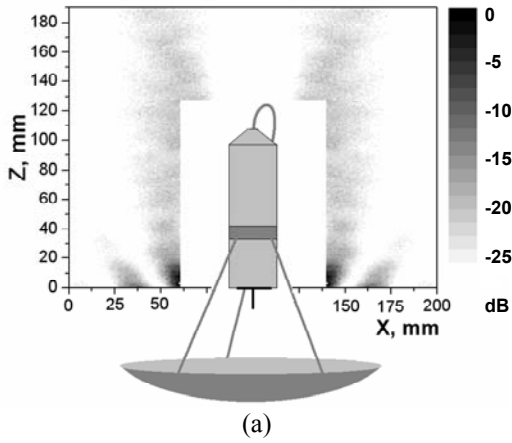


Fig. 7. Measured (a) and calculated (b) near-field distribution of the reflector-type antenna prototype.

3. Direction-Finder Prototype

In order to realize the reflector antenna operation in the received mode we have integrated the one-stage HEMT based amplifier in the input antenna circuit. The conceptual block-diagram of the direction-finder system is shown in Fig. 8. The signal received from the SHF source goes into the low-noise amplifier for the signal pre-amplification within the antenna bandwidth. Next logarithmic amplifier realizes the signal amplification to the level to be quite enough for the effective ultra wideband video detector operation ($U=1$ mV). The wideband low-noise video amplifier with a small integration time constant ($\tau=0.1 - 1$ microseconds for the choice) increases the signal up to the level required to the stable flash encoder operation (around 2.5 V). After video-amplifier the signal enters the interface and then on the working board of the control unit. The photo of the control unit is shown in Fig. 9.

There are two operating modes of the direction-finder, namely: (i) first, the rough determination of the source location on the maximum level of the received signal (so-called the “search mode”); (ii) second, the accurate determination of the source location on the global minimum of the received signal (so-called the “bearing mode”). In this case the arrangement of the light-emitting

diodes on the working board of the control unit in the shape of V-symbol simulates the aforementioned bearing algorithm (Fig. 10).

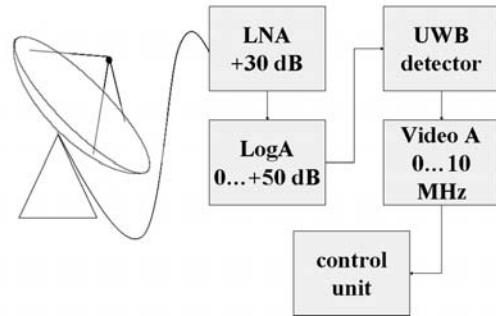


Fig. 8. Block-diagram of the direction finder system.



Fig. 9. Control unit.

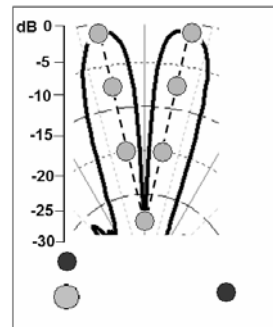


Fig. 10. Bearing angle imitator panel.

4. Model Experiments

We have carried out the model experiments on the SHF source bearing by means of the aforementioned direction-finder prototype. The open-ended X-band waveguide was located at the distance of 20 m from the direction-finder. We measured the angular dependences of the received signal power in the frequency band 6 to 11 GHz. Based on the analysis of experimental angular dependencies, which have been found to be similar to those depicted in Fig.10, we can pronounce that in the examined frequency band the power signal ratio in the antenna axis and in the main lobe maximum do not exceed -20dB. The measurement results allow one to determine the accuracy of the source bearing approximate 2degree.

5. Conclusions

A novel design of the compact broadband direction-finder is presented. We have optimized the geometric parameters of the reflector antenna for its effective utilizing as a direction-finder antenna. The good matching of the reflector antenna to 50 Ohm feeding line has been achieved in the antenna bandwidth 6 GHz – 11 GHz. The results of simulations and model experiments demonstrate the capability and benefits of the proposed direction-finder.

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